

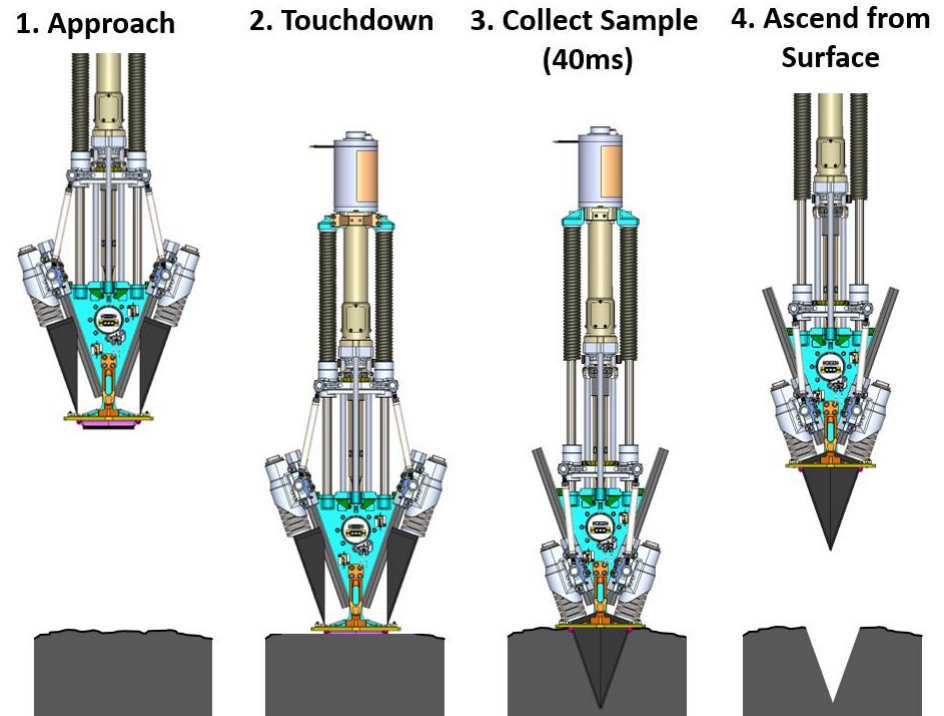
# ***The BiBlade Sample Chain and Experimental Results for Comet Surface Sampling***

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Jet Propulsion Laboratory  
California Institute of Technology**

**May 10, 2017**

# Touch-and-Go Mission Concept Architecture

- Spacecraft maneuvers to several meters from surface of comet.
- Sampler is at end of robotic arm.
- Spacecraft descends until sampler contacts surface of comet.
- Acquire sample.
- Ascend away from comet.



# Comet Surface Sample Return Requirements from the Decadal Survey

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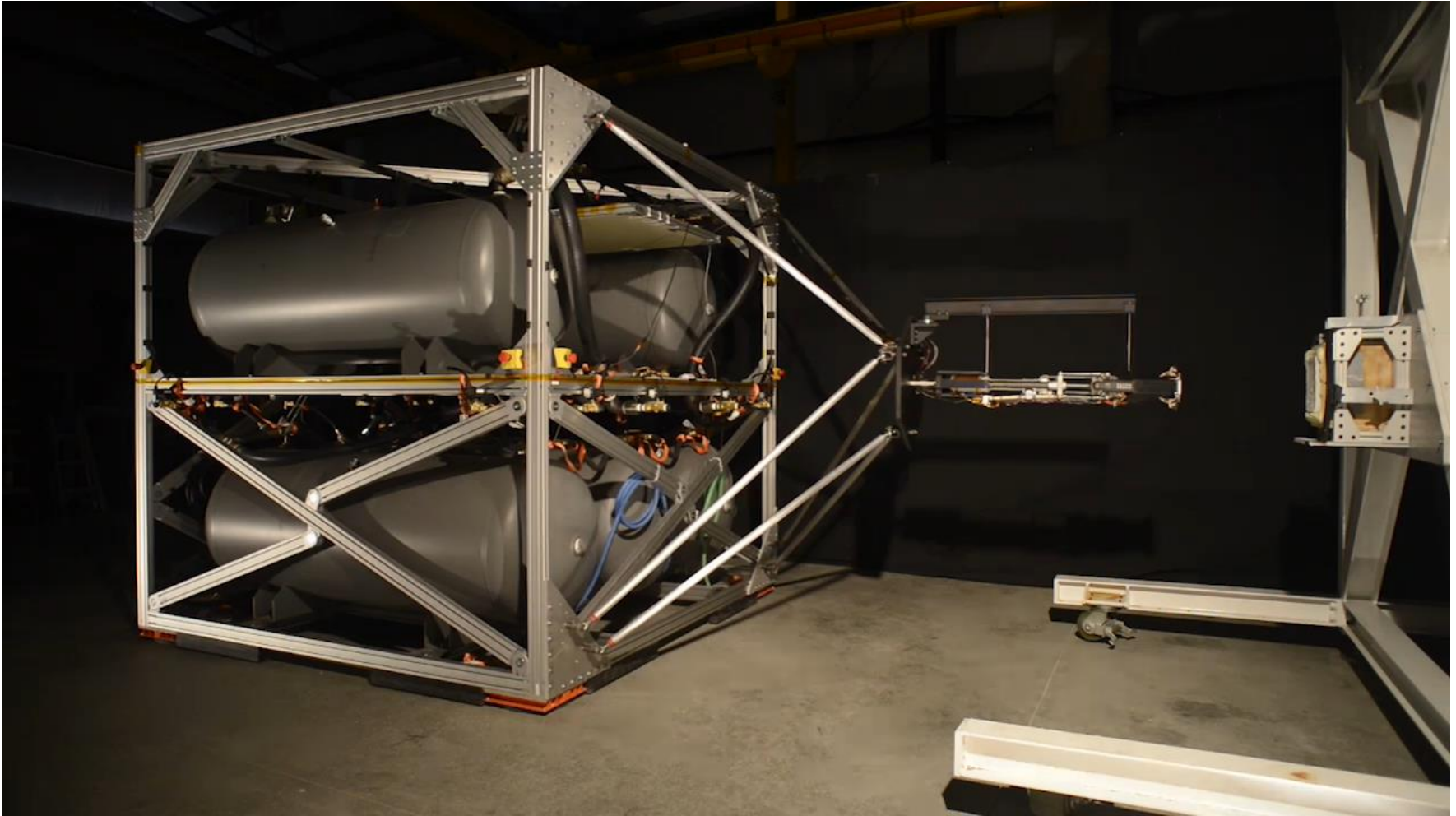
## Group 1: From the Decadal Survey Primary Document

- Return a single  $\geq 500$  cc sample from the surface of any comet nucleus
- Preserve sample complex organics (sample using a “soft” technique)
- Prevent aqueous alteration of the sample at any time (maintain at  $\leq -10^{\circ}\text{C}$ )

## Group 2: In Decadal Survey Appendix Mission Study Document

- If the sampled region has shear strength  $\leq 50$  kPa
  - Return material from depth  $\geq 10\text{cm}$  ( $\sim 3$  diurnal thermal skin depths)
  - Maintain sample stratigraphy
- Determine whether the sample is from an active or inactive nucleus region

# Full-scale Sampling Validation





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# Sample Chain



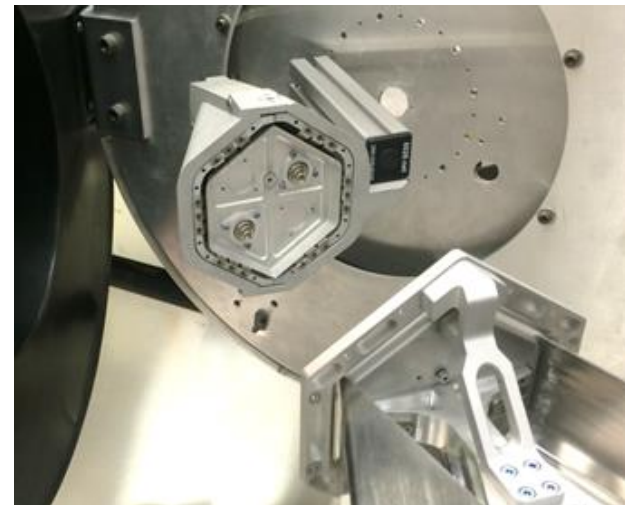
Pull blades back compressing springs  
(one actuator for all operations)



Sample in  $\sim 30$  ms (fast) and retract  
(tapered blades prevent binding)



Insert into sample measurement station  
and image with 9 fiberscopes



Insert into SRC and release lid via  
frangibolt (repeat for second sample)

Predecisional, for planning and discussion purposes only

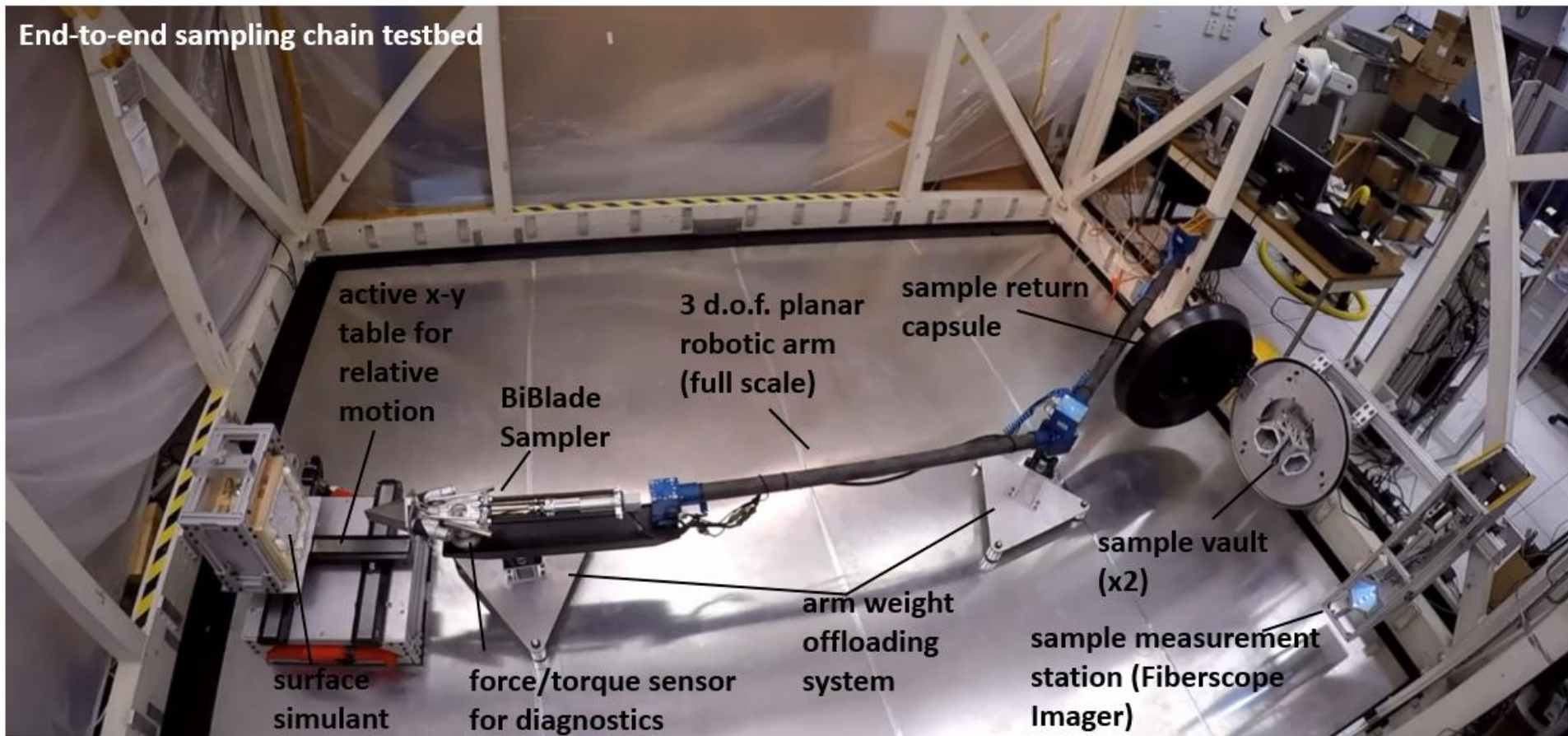




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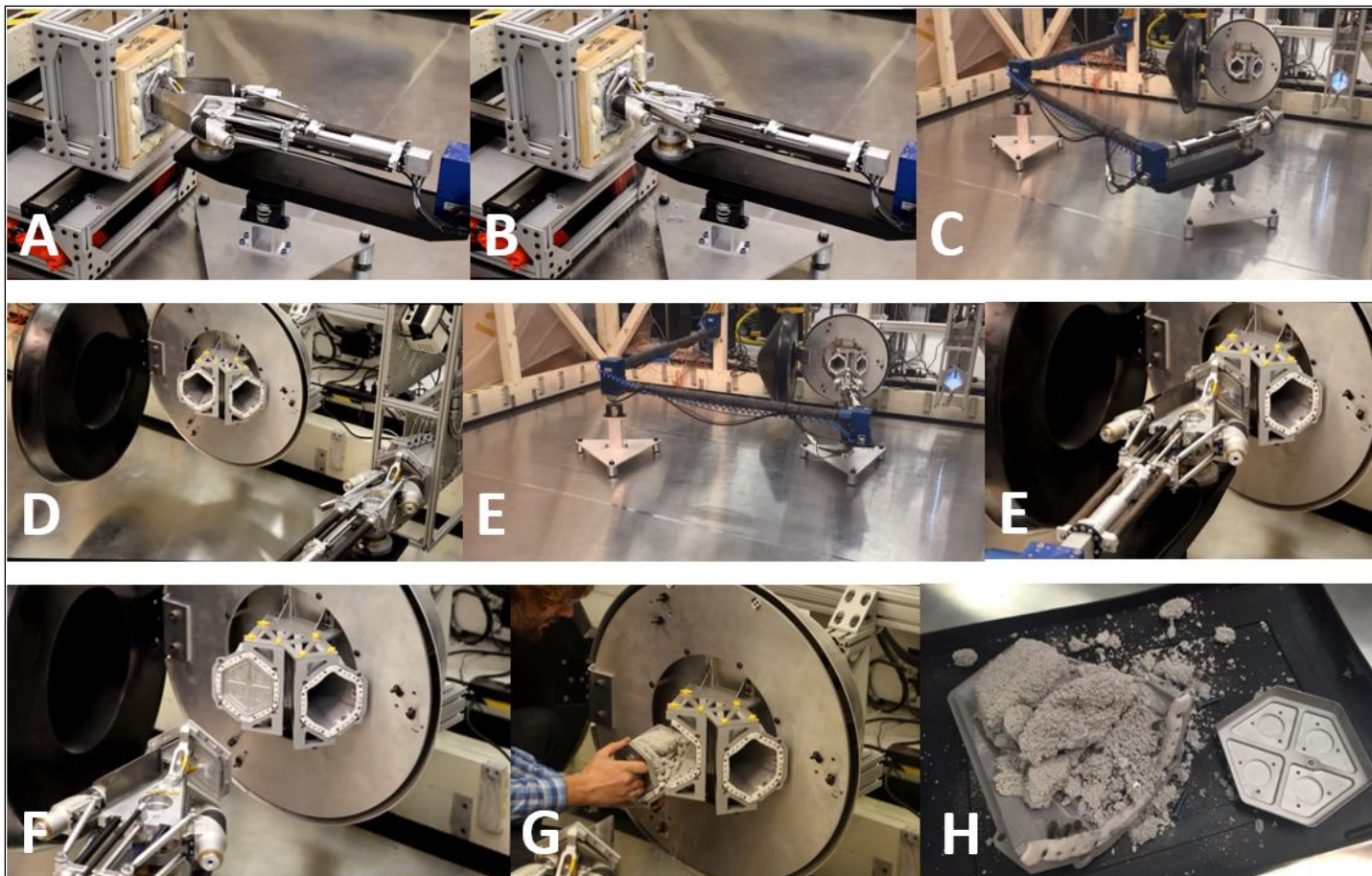
# End-to-end Sampling Chain Testbed

End-to-end sampling chain testbed





# BiBlade Sampling Chain



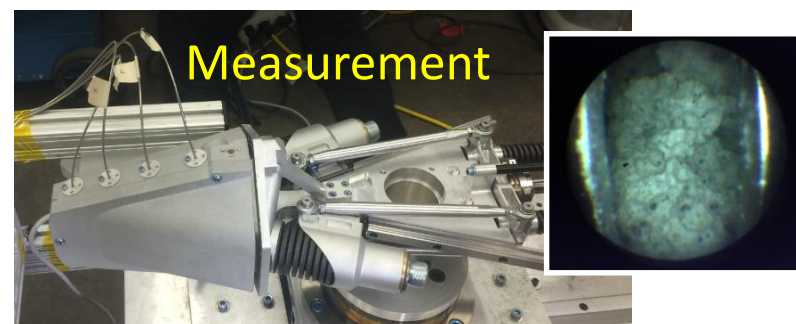
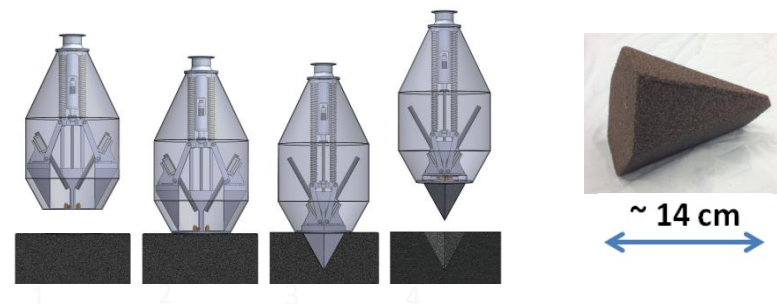
**(A)** Approach; **(B)** Springs drives blades into simulant; **(C)** Transfer to Sample Return Capsule (SRC); **(D)** Sample measurement using Fiberscope Sample Imager; **(E)** Insert BiBlade into SRC vault and retract blades; **(F)** Fire Frangibolt to release lid and contain sample; **(G)** Retract; **(H)** Show results by opening sample vault and displaying acquired sample.



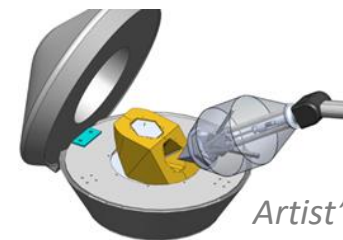


# BiBlade Features

- Sample volume: 500 cc
- Depth: 10% below 10 cm
- Sample strength: 0 - 5 MPa CPR
- Sampling and encapsulation in ~40 ms
- Acquires and stores two samples from two separate sites
- Enables multiple attempts per sample
- Fully tapered blades for robust extraction from comet
- Direct measurement of sample with nine-fiberscope imaging
- Mechanically simple requiring only one actuator and two frangibolts



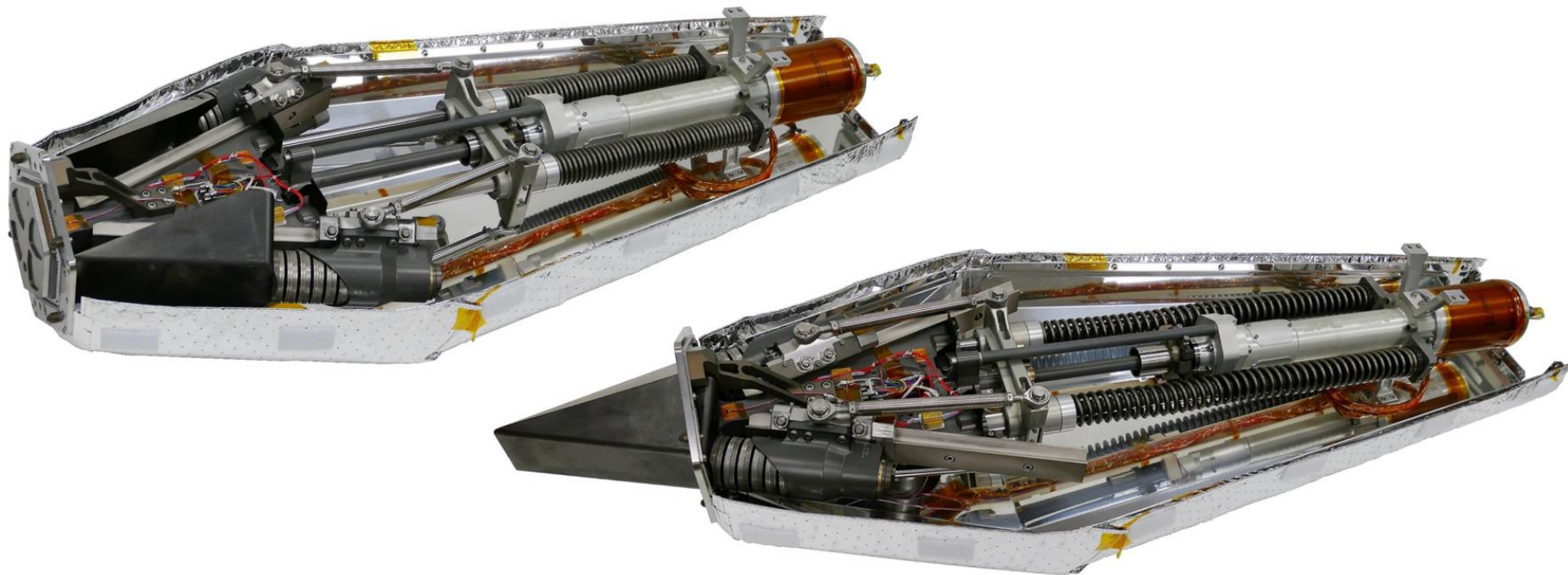
Insert  
into SRC





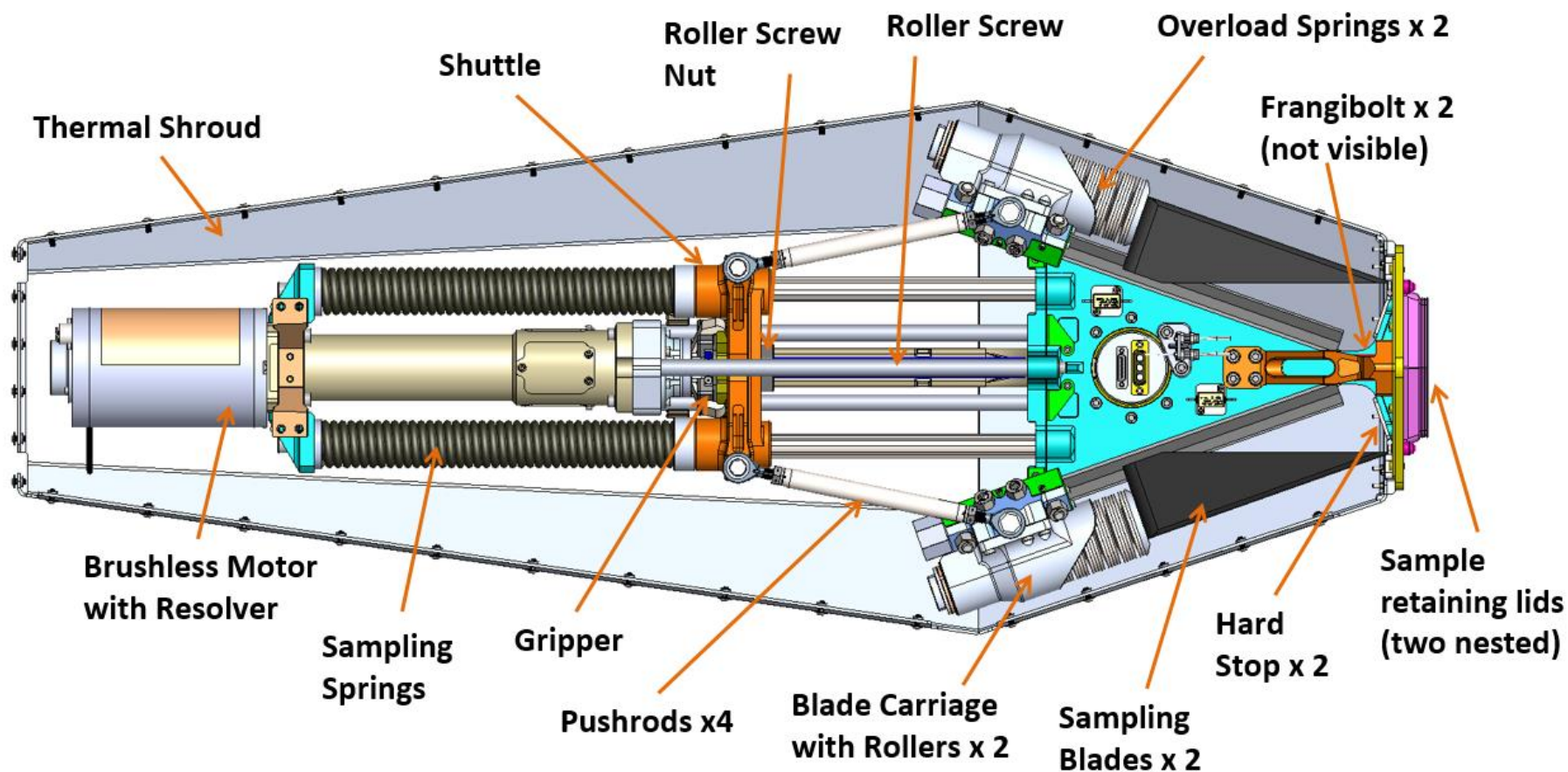


# BiBlade Design



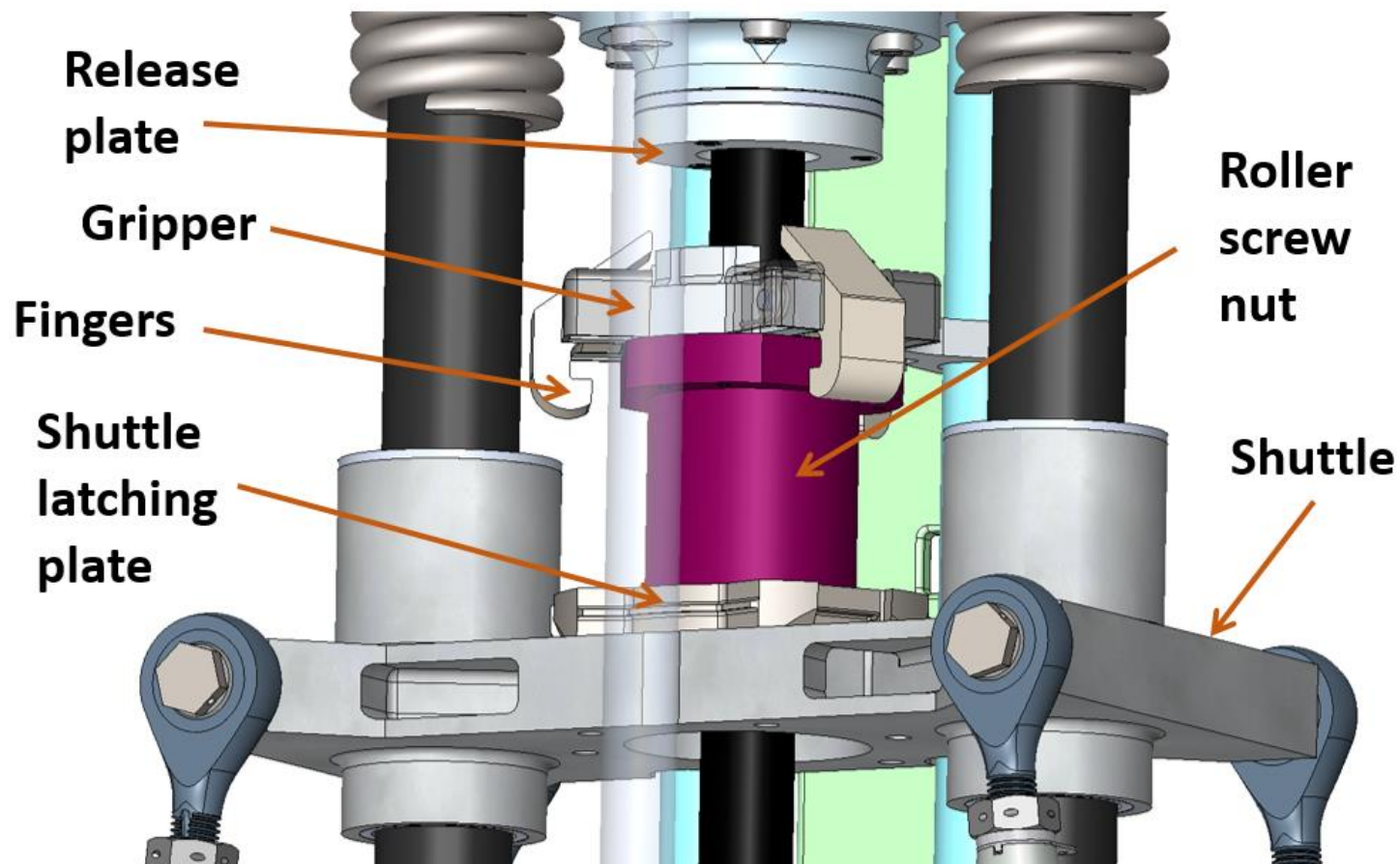


# BiBlade Design





# Gripper Mechanism





# Mechanical Porous Ambient Comet Simulant (MPACS)

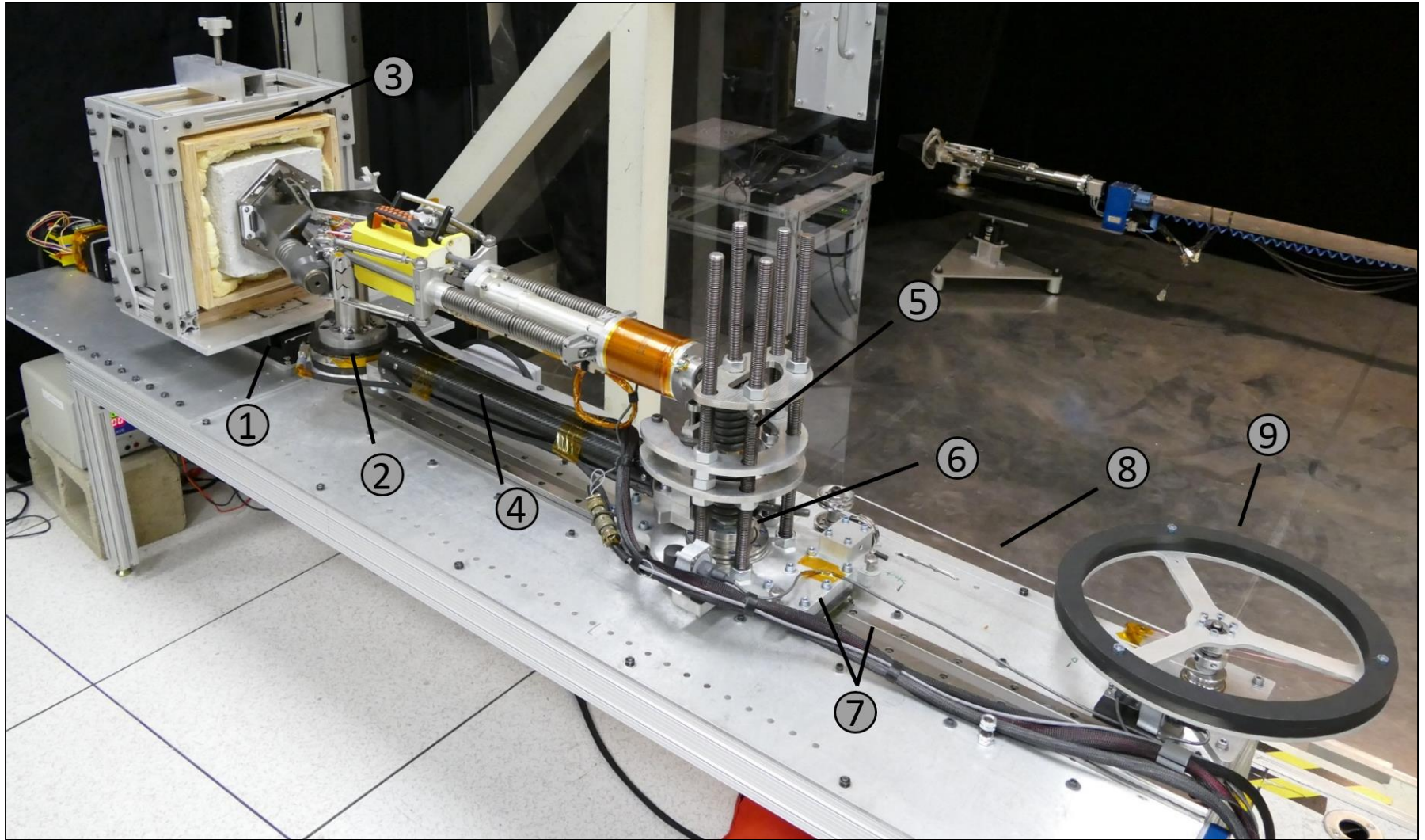
- Ingredients: Portland cement and pumicite combined and added to water and a foaming agent.
- Strength properties were varied by changing the amount of foaming agent added to the mixture.
- The MPACS material was fabricated into 8-inch cubic boxes for the BiBlade test program.
- Density, cone penetration resistance (CPR), uniaxial compressive strength (UCS), shear strength, and porosity were measured.





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# Sampling Testbed



Predecisional, for planning and discussion purposes only

# Low End Sampling Results – Sampling Into Fly Ash

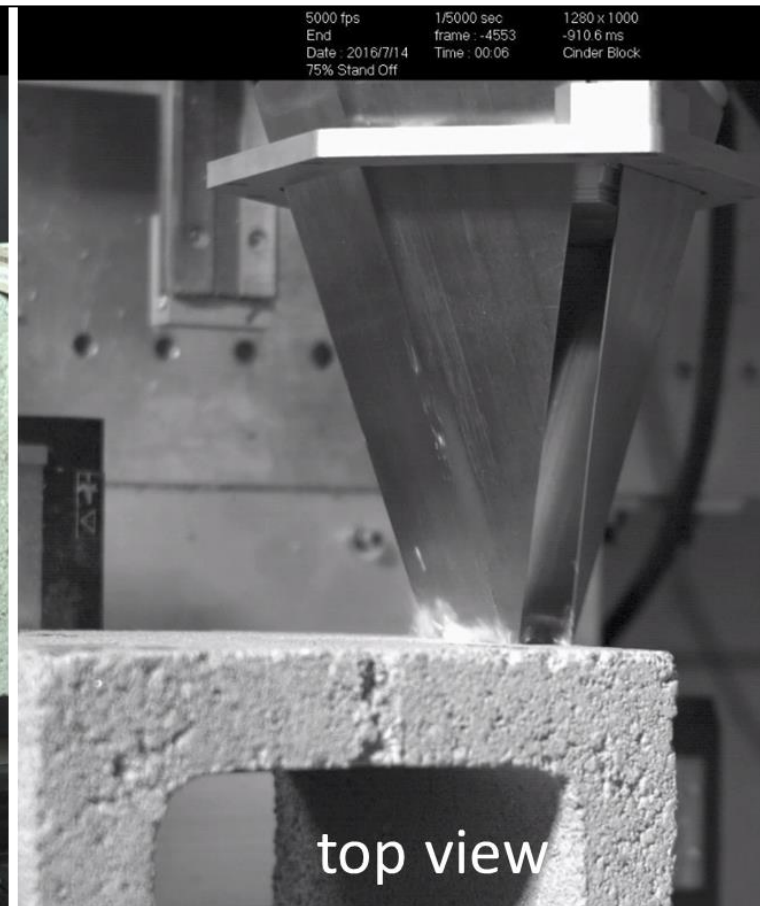
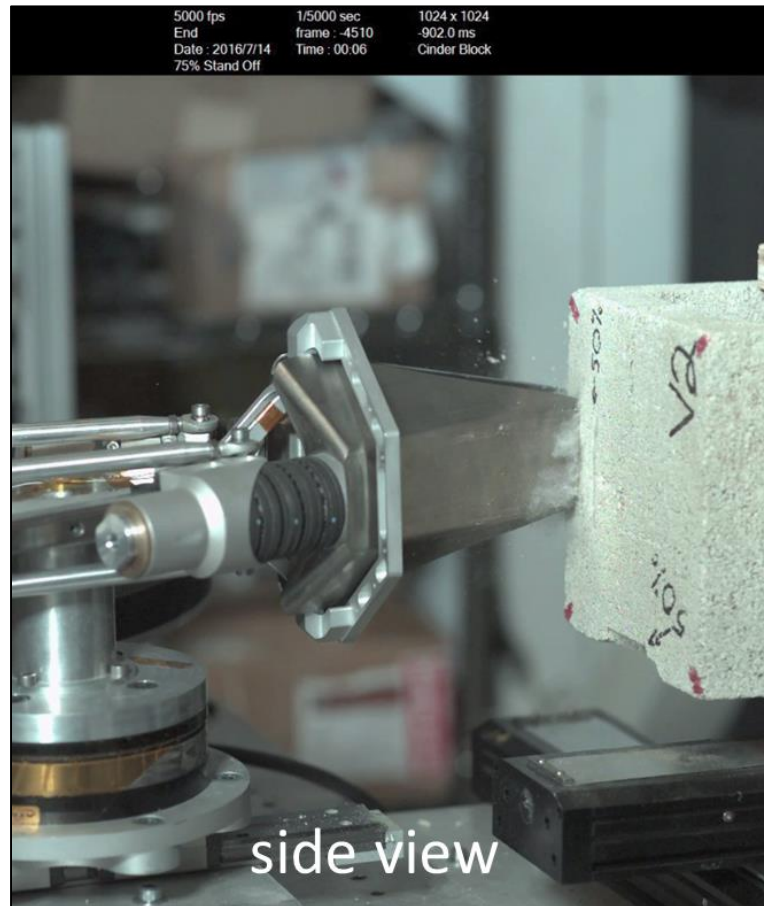


- Ejecta plate redirects ejecta to the side, away from spacecraft

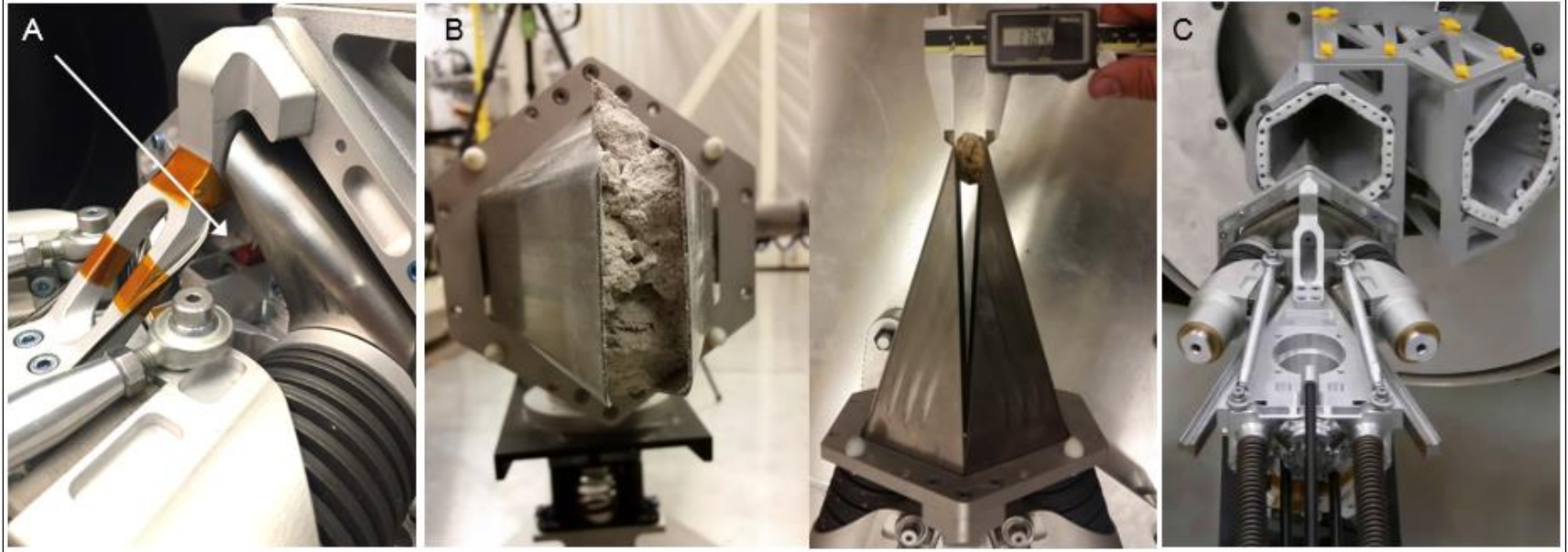


# Survive Hitting Hardest Material

Tool survives hitting cinder block at maximum blade velocity, having only one blade strike. Overload springs absorb impact energy.



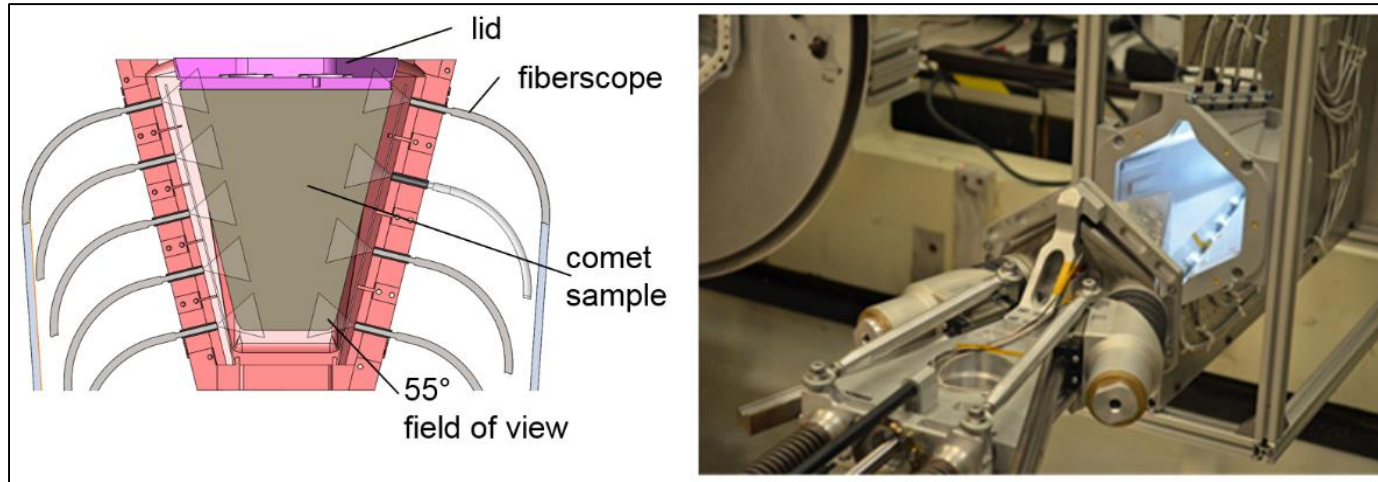
# Robustness to Off-nominal Samples and Transfer Conditions



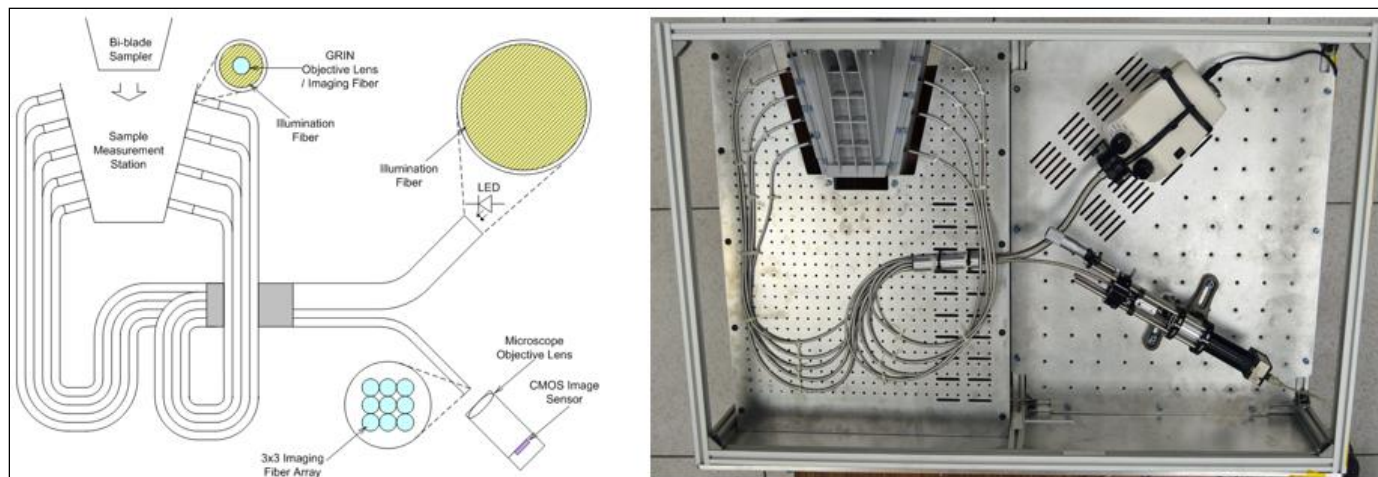
Robustness testing of sample transfer process/hardware.

- (A) Frangibolt actuation is included in the sample lid release.
- (B) Off-nominal samples are forced to test insertion and stowage robustness to extreme scenarios.
- (C) Positional error was intentionally commanded to evaluate limits of self-alignment during tool insertion.

# Sample Measurement: Fiberscope Sample Imager



Nine fiberscopes along the walls of the measurement chamber passively transfer views of the sample surface to a common camera



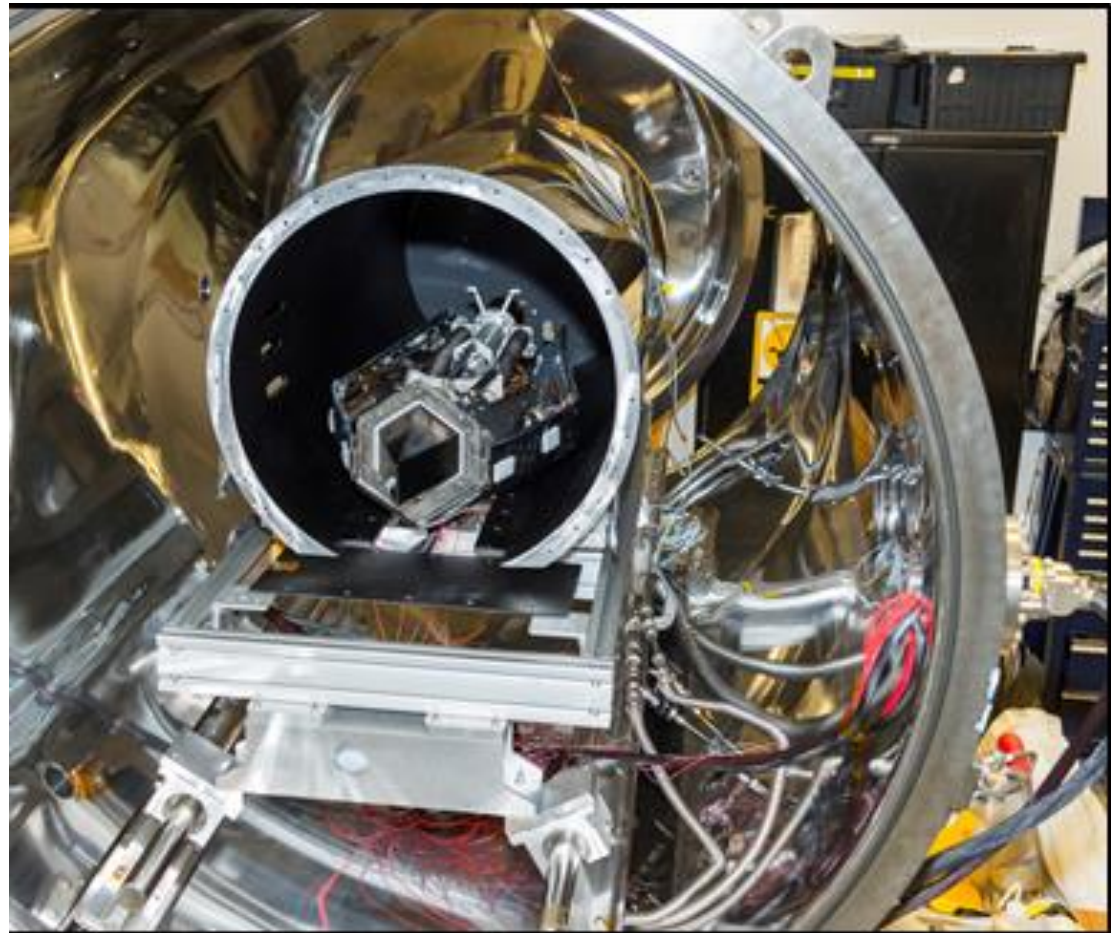




# Thermal Vacuum Chamber Testing

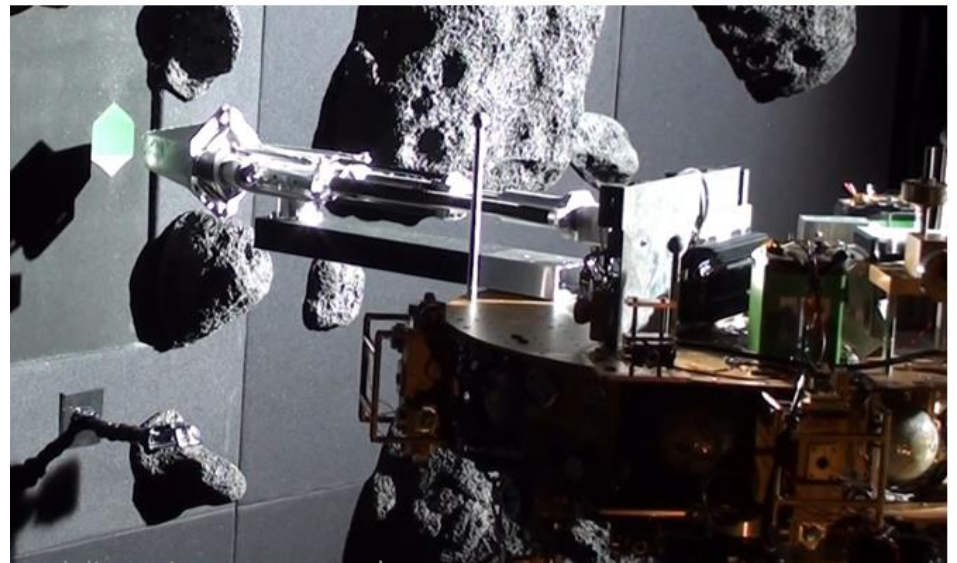
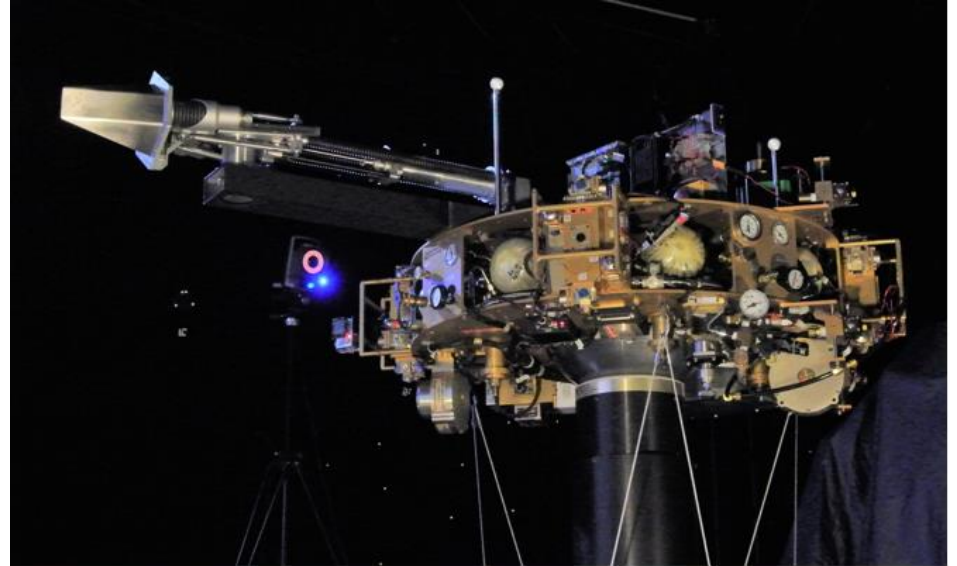
- Cycling between +70°C and -160°C (three cycles)
  - Sampler thermal control system maintained cold phase tool temperatures between the thermostat set points, -32°C to -25°C
- Pressure  $10^{-7}$  torr (high vacuum)
- Functional testing
  - Actuator homing s at each cold cycle
  - Functional test at last cold phase consisting of self-fire sampling operations five times
- Performance verification
  - Verify thermocouples read values within allowable flight temperatures of the components
  - Verify surfaces contacting sample (blades) do not exceed -25°C
  - Verify that actuator maintains adequate torque/current margin
  - Verify kinetic energy available for sampling (blade speed) within 5% of Standard Temperature/Pressure condition

Cold shroud end plate and top half of BiBlade thermal/dust shroud removed for photo.



# Integrated Proximity Operations and Sampling

- Mounted BiBlade on air-levitated robotic spacecraft and demonstrated autonomous Touch-and-Go approach, sampling, and ascent.
- In JPL Formation Control Testbed.



# Contributors

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